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Infinite horizon optimal control. Theory and applications. (English) Zbl 0649.49001

Lectures Notes in Economics and Mathematical Systems, 290. Berlin etc.: Springer-Verlag. XI, 254 p.; DM 52.00 (1987).

The main problem of the research in the monograph is a qualitative analysis of the behavior of optimal trajectories, in the first place a convergence to the point of phase space which is a solution of a static optimization problem. The statements on this convergence are usually called turnpike theorems.

Chapter 1 gives examples of optimal control problems on unbounded time intervals in the field of economics, ecology and technology. The definitions of optimal control are introduced with a meaning for divergence of integrals in the optimality functional.

Chapter 2 presents necessary and sufficient conditions for optimality in the form of a maximum principle for trajectories with infinite horizon duration.

Chapter 3 presents some problems where turnpike behavior of optimal trajectories can be fixed with the help of simple devices.

Chapter 4 considers convex autonomous problems with the help of large variations of trajectories. Autonomous systems with a nonautonomous functional of optimality, where the nonautonomous component is a decreasing exponent, are considered in chapter 5.

Chapter 6 gives statements on the convergence of optimal trajectories for nonautonomous and nonconvex problems.

Chapter 7 is devoted to the existence of solutions on infinite time intervals for nonautonomous control systems.

Chapter 8 analyses optimal processes with infinite time for linear equations with distributed parameters interpreted as usual differential equations in Hilbert space.

The book will promote the development of a new trend in optimal control connected with qualitative research of optimal processes of large and infinite duration [see also, the reviewer, *Avtom. Telemekh.* 1983, No.9, 58-66 (1983; [Zbl 0562.93055](#)); *ibid.* 1981, No.8, 119-130 (1981; [Zbl 0489.93036](#)); and the reviewer together with *A. I. Panasyuk*, *Prikl. Mat. Mekh.* 49, 524-535 (1985; [Zbl 0614.49015](#))].

Reviewer: [V.Panasyuk](#)

MSC:

- [49-02](#) Research exposition (monographs, survey articles) pertaining to calculus of variations and optimal control
- [49J15](#) Existence theories for optimal control problems involving ordinary differential equations
- [49K15](#) Optimality conditions for problems involving ordinary differential equations
- [93C15](#) Control/observation systems governed by ordinary differential equations
- [93C20](#) Control/observation systems governed by partial differential equations
- [93C25](#) Control/observation systems in abstract spaces
- [49J20](#) Existence theories for optimal control problems involving partial differential equations
- [49J27](#) Existence theories for problems in abstract spaces
- [49K20](#) Optimality conditions for problems involving partial differential equations
- [49K27](#) Optimality conditions for problems in abstract spaces

Cited in **2** Reviews
Cited in **24** Documents

Keywords:

behavior of optimal trajectories; turnpike theorems; maximum principle; infinite horizon; convex autonomous problems; convergence of optimal trajectories; nonautonomous and nonconvex problems; linear equations with distributed parameters